

An Itchiness of ICRA Papers, and a Mass of AAMAS Papers

The last official seminar of the 2023/24 academic year will be a celebration of some of the work that the Robotics Program published at the AAMAS 2024 and ICRA 2024 conferences.

Learning Vision-Based Bipedal Locomotion for Challenging Terrain, Helei Duan, Bikram Pandit, Mohitvishnu S. Gadde, Bart van Marum, Jeremy Dao, Chanh Kim, Alan Fern. Presented by Mohit Gadda

WAVE: An open-source underWater Arm-Vehicle Emulator, Marcus Rosette, Hannah Kolano, Chris Holm, Geoffrey A. Hollinger, Aaron Marburg, Madison Pickett, Joseph R. Davidson. Presented by Marcus Rosette

Dynamic evaluation of a suction-based gripper for fruit picking using a physical twin, Alejandro Velasquez, Cindy Grimm, Joseph R. Davidson. Presented by Alejo Velasquez

Influence-Focused Asymmetric Island Model, Andrew Festa, Gaurav Dixit, Kagan Tumer. Presented by Gaurav Dixit

Sim-to-Real Learning for Humanoid Box Loco-Manipulation, Jeremy Dao, Helei Duan, Alan Fern. Presented by Jeremy Dao

Indirect Credit Assignment in a Multiagent System, Everardo Gonzalez, Siddarth Viswanathan, Kagan Tumer. Presented by Sidd Viswanathan



FRIDAY
Jun 7
10-11AM

Rogers Hall 230
FREE
Refreshments Served

OSU Robotics
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