

Four Talks about Robots (IROS Edition)

Scott Chow
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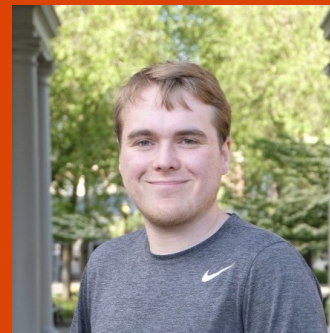
This week, we have four short talks representing the diversity of research that we do here in the Robotics Program. All of these talks present work that recently appeared in the International Conference on Robots and Systems (IROS 2023).

Parallelized Control-Aware Motion Planning with Learned Controller Proxies, Chow, Chang, and Hollinger.

Hand Design Approach for Planar Fully Actuated Manipulators, Nave, DuFrene, Davidson, and Grimm.

Robottheory Fitness: GoBot's Engagement Edge for Spurring Physical Activity in Young Children, Mayoral, Helmi, Warren, Logan, and Fitter.

Geometric Gait Optimization for Inertia-Dominated Systems with Nonzero Net Momentum, Yang and Hatton.



FRIDAY
Oct 13
10-11AM

KEC 1001
FREE
Refreshments Served

OSU Robotics
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