

# An Itchiness of ICRA Papers, and a Mass of AAMAS Papers

The last official seminar of the 2023/24 academic year will be a celebration of some of the work that the Robotics Program published at the AAMAS 2024 and ICRA 2024 conferences.

**Learning Vision-Based Bipedal Locomotion for Challenging Terrain**, Helei Duan, Bikram Pandit, Mohitvishnu S. Gadde, Bart van Marum, Jeremy Dao, Chanh Kim, Alan Fern. Presented by Mohit Gadda

**WAVE: An open-source underWater Arm-Vehicle Emulator**, Marcus Rosette, Hannah Kolano, Chris Holm, Geoffrey A. Hollinger, Aaron Marburg, Madison Pickett, Joseph R. Davidson. Presented by Marcus Rosette

**Dynamic evaluation of a suction-based gripper for fruit picking using a physical twin**, Alejandro Velasquez, Cindy Grimm, Joseph R. Davidson. Presented by Alejo Velasquez

**Influence-Focused Asymmetric Island Model**, Andrew Festa, Gaurav Dixit, Kagan Tumer. Presented by Gaurav Dixit

**Sim-to-Real Learning for Humanoid Box Loco-Manipulation**, Jeremy Dao, Helei Duan, Alan Fern. Presented by Jeremy Dao

**Indirect Credit Assignment in a Multiagent System**, Everardo Gonzalez, Siddarth Viswanathan, Kagan Tumer. Presented by Sidd Viswanathan



FRIDAY  
Jun 7  
10-11AM

Rogers Hall 230  
FREE  
Refreshments Served

OSU Robotics  
[robotics.oregonstate.edu](https://robotics.oregonstate.edu)



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